Wireless Power and Data Transfer via a Common Inductive Link Using Frequency Division Multiplexing

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Abstract—For wireless power transfer (WPT) systems, communication between the primary side and the pickup side is a challenge because of the large air gap and magnetic interferences. A novel method, which integrates bidirectional data communication into high power WPT system, is proposed in this paper. The power and data transfer share the same inductive link between coreless coils. Power/data frequency division multiplexing technique is applied, and the power and data are transmitted by employing different frequency carriers and controlled independently. The circuit model of the multi-band system is provided to analyze the transmission gain of the communication channel, as well as the power delivery performance. The cross-talk interference between two carriers is discussed. Besides, the signal-to-noise ratios (SNR) of the channels are also estimated, which gives a guideline for the design of mod/demod circuits. Finally, a 500W WPT prototype has been built to demonstrate the effectiveness of the proposed WPT system.

Index Terms - Wireless power and data transfer, near field magnetic communication, multi-band system, frequency division multiplexing.

I. INTRODUCTION

With the development of electronics, the wireless power transfer (WPT) technology has been widely adapted for advantages of convenience and safety. Since the 1960's, the WPT technique has been applied in biomedical fields which made a great progress for human health care [1]-[2]. In the field of consumer electronics, wireless charger is becoming popular and several WPT standards have been set up to increase the interoperability of different chargers [3]-[5]. For high power application such as electrical vehicles (EVs) chargers and grids interface [6]-[11], the WPT technique enhances the devices safety and decreases the connectivity complexity.

For most applications, reliable communication between the primary side and the pickup side plays an essential role in a well-designed WPT system. For instance, the functions such as output voltage feedback control, load detection, status monitoring, auto-tuning and multi-controllers synchronization are generally required in WPT systems [12-17], which can be implemented more easily if the communication between both sides is provided. Radio frequency (RF) link is a common way employed in many WPT systems for wireless communication [12-13], but it leads to higher costs and lower reliability with increasing power rating of WPT system.

Several methods have been proposed to transfer power and data from the same inductive link. For example, in some low power cases, the inherent inductive link for power transfer is exploited as an antenna for data transmission, where the data is directly modulated on the power carrier by frequency shifting keying (FSK) in forward data transmission, and the load-shift keying (LSK) technique is adopted to achieve backward data transmission [18]. However, the techniques that employ a single carrier for both power and data transfers have two major drawbacks. The first one is that the data rate is limited by the frequency of the carrier. For the systems using power-carrier frequency below 50kHz, the data rate should not exceed several kbps. The second drawback is that the FSK technique used for forward communication decreases the power transmission efficiency since the operation of system shifts from its optimal points, so FSK/LSK technique is not suitable for the application of high power WPT system.

Several methods of using multiple inductive links with multiple carriers have been proposed to increase the data rate and maintain the efficiency of power transfer [19]-[24]. In these methods, power and data are transferred via independent physical channels, where the power carrier is delivered through one inductive link and the data carrier is transmitted via another. However, multiple links will cause extra magnetic interferences between the two channels. The strong power carrier is regarded as a large noise for small data signal, which decreases the signal-to-noise ratio (SNR) in communication channel. Multiple inductive links also lead to larger device size, which is undesirable for confined space applications.

The scheme with multiple carriers in a single inductive link is another candidate for WPT systems, in which two tuning
points in both sides facilitate the data transmission while eliminating extra coils. In [25]-[27], wireless power and data transmission is achieved between the primary and secondary side of a strong coupled inductor, whose air gap is less than 1mm. In this method, a high frequency data carrier is overlapped on the power carrier for communication during non-switching period of the power inverter. This scheme is equally applicable for loosely coupled WPT systems [28], but detailed communication models and specific circuit designs are not discussed in previous papers.

In this paper, a novel system with multiple carriers in a single inductive link is proposed for wireless power and data transmission, and the detailed mathematical model of the proposed multi-band system is presented and analyzed. This method is applicable for high power WPT system operating in several tens kHz, and the data-carrier frequency is selected at least an order of magnitude higher than power frequency. There are several advantages compared with other methods: (1) The structure of the system is simple and no extra coil is needed; (2) The control of power converter and data communication is independent with each other; (3) The mutual inductance of the coils can be calculated on line by measuring the amplitude of the received data carrier, which can be utilized to estimate the distance of the two coils.

The cross-talk interference between power and data channel in the dual-tuning system that aims to achieve high power transmission efficiency and reliable bidirectional communication is discussed in detail. Moreover, a low-cost circuit design is provided to implement the proposed frequency division multiplexing technique. The effectiveness of the proposed WPT system is verified by experimental results from a 500W WPT prototype.

II. SYSTEM OVERVIEW

The block diagram of the proposed system is shown in Fig.1. The system is divided into two parts: the primary side and the pickup side. The inductive link bridges the primary side and the pickup side, which is indispensable for wireless power transfer. A full bridge inverter on the primary side delivers power to the load via the inductive coils, and a rectifier is employed on the pickup side to converts the inductive energy into DC output voltage.

The proposed communication cell, which is shown in Fig.2, is adopted in both sides and magnetically coupled with power resonant tank by the ferrite-core coupled inductors. The communication cells have two operation modes: transmitter mode and receiver mode, which is controlled by an electronics switch. At transmitter mode, a signal amplifier is employed as a data source to transmit data. At receiver mode, an impedance matching network is connected to receive the data carrier from the other side, and the data is demodulated and read by a MCU. Thus, the system can work in two statuses: forward communication status and backward communication status. In forward communication status, the primary side is working on transmitter mode and the pickup side is working on receiver mode; in backward communication status, the primary side is working on receiver mode and the pickup side is working on transmitter mode.

For a WPT system, SS, SP, PP and PS are basic structures which are classified according to the different LC branches (serial and parallel) in primary side and pickup side. The proposed communication cell can be inserted to a serial LC branch or a parallel LC branch, so the proposed method is applicable for SP, SS, PP and PS topology WPT circuits. In this paper, the SP (primary series, secondary parallel compensation) topology is employed as an example of wireless power and data transfer system.

The schematic diagram of the proposed system is shown in Fig.3 for backward communication and in Fig.5a for forward communication. \(L_1\) and \(R_1\) are the inductor and resistor of the primary inductive coil, and \(C_1\) is the series compensation capacitor. \(L_2\) and \(R_2\) are the inductor and resistor of the pickup winding and \(C_2\) is the parallel compensation capacitor. The inductive coils are made of Litz wire to reduce AC resistances. \(L_3\) and \(L_4\) are coupled inductors for data carrier coupling. The frequency of power carrier is set at 22.4kHz and the data carrier is set at 1.67MHz. In the proposed method, the data-carrier frequency should be at least an order of magnitude higher than power frequency, that because: (1) Only in this condition, the voltage drop of power carrier on the communication cell is quite small, so the power transfer efficiency would not be significantly decreased by the communication cell; (2) The cross-talk interference of data communication from power transfer is suppressed, so as to facilitate the design of demodulation circuit and guarantee the reliability of communication.

The specific parameters of the circuit are given in Table I.
III. POWER DELIVERY ANALYSIS

Because extra communication components are added to the power resonant tank, it is necessary to evaluate the performance of power delivery and the cross effect introduced by the data transmission. In the following analysis, it is assumed that the data-carrier frequency is much higher than the power frequency, and the inductance of the signal coupled inductor is much lower than that of the inductive coil.

A. Coupled Inductor Impact

The circuit model of the SP topology is shown in Fig.4. $V_p$ is the inverter output voltage, which is simplified as a sinusoidal voltage source by neglecting higher order harmonics. The rectifier with load is simplified as an equivalent resistance $R_e$. In addition, at the power-frequency $f_p$, the impedances of the signal coupled inductor $L_1$ and $L_2$ are much smaller than the reflected impedances of $C_1$ and $C_2$, so the equivalent circuit of communication cells is simplified as an inductor. $L_{1-4}$ are composed of the magnetizing inductor $L_{m1-4}$ and leakage inductor $L_{l1-4}$, which are involved in power resonance.

By analysing the impacts of coupled inductors on power transfer operation in steady state and ignoring the data carrier, the circuit equations of Fig.4 are:

$$
\begin{align*}
V_p &= (j\omega L_1 + j\omega L_3 + \frac{1}{j\omega C_1} + R_1)I_1 - j\omega MI_2 \\
0 &= (j\omega L_2 + j\omega L_4 + \frac{1}{j\omega C_2} + \frac{1}{R_e})I_2 - j\omega MI_1
\end{align*}
$$

When the switching frequency of the inverter is tuned to the circuit resonant frequency, the primary inductance ($L_1 + L_3$) and the pickup side inductance ($L_2 + L_4$) are compensated by $C_1$ and $C_2$. The resonant angular frequency $\omega_r$ of the proposed system is expressed as:

$$
\omega_r = \frac{1}{\sqrt{(L_1 + L_3)C_1}} = \frac{1}{\sqrt{(L_2 + L_4)C_2}}
$$

$L_1$ and $L_4$ have a small number of turns and small ferrite-core volumes, so the copper loss and core loss of the coupled inductors have small influence on the power transmission efficiency and overall output power. If the losses on the coupled inductors are ignored, the power delivery performance of the proposed system is similar to the conventional circuits without communication, which is given in [7].

B. Operation Preconditions for Data Carrier

It is assumed that energy transfer is not influenced by data transmission in the proposed system. However, the data carrier could bring about interference to the inverter output and reduce the system efficiency. In this section, the impact of the data carrier on the power transmission is discussed.

The schematic diagram of forward data transmission circuits is shown in Fig.5 (a). The primary side current is composed of two parts: power-carrier current $i_p$ and data-carrier current $i_d$, which corresponding to the inductor current in Fig.5 (b) and Fig.5 (c).

Assuming the switches $Q_{1-4}$ are ideal with no parasitic capacitor, the data carrier injected from the coupled inductor may change the current path, which causes voltage spikes in the inverter output. The voltage spikes would be induced if the two preconditions are satisfied: 1) During the dead-time of the two
legs, the current is approaching to zero, which means that the equivalent load of the inverter is almost resistive. 2) The current slew rate of data carrier is higher than that of the power current at the period of dead-time.

The occurrence condition and the waveforms of the spikes are shown in Fig.6. In Stage 1 [t1, t2], Q1 is open and Q2, Q4 are closed. The current path of the \( L_{C1} \) loop is determined by the polarity of the current \( i_p+i_d \). For \( i_p \) being a high frequency current, if \( i_p+i_d > 0 \), the current flows through MOSFET \( Q_1 \) and the diode in \( Q_2 \), so the output voltage \( V_p \) of the inverter is zero. If \( i_p+i_d < 0 \), the current passes through \( Q_1 \) and the diode of \( Q_2 \), so the output \( V_p \) equals to \( V_m \), which leads to spikes of inverter output in the dead-time period.

In Stage 2 [t2, t4], \( Q_1 \) and \( Q_2 \) are turned on. Although the polarity of \( i_p+i_d \) changes, the current path is fixed to \( Q_1 \) and \( Q_2 \), which will not cause output spikes in the primary inverter.

From the above analysis, it is concluded that the spikes may occur at the period of dead-time. Assuming \( i_p \) and \( i_d \) are sinusoidal,

\[
i_p(t) = I_p \sin(\omega_p t + \theta_p)
\]

\[
i_d(t) = I_d \sin(\omega_d t + \theta_d)
\]

where \( I_p \) and \( I_d \) are the amplitude of the power carrier and data carrier respectively.

Assuming the current amplitude of the power carrier is much greater than data carrier, the sufficient condition which can avoid the spike influenced by data carrier is: the slew rate of the power carrier at zero crossing point should be greater than the slew rate of the data carrier at any time, which can be expressed as

\[
\left| \frac{di_p(t)}{dt} \right|_{|\omega_p^*|} > \left| \frac{di_d(t)}{dt} \right|_{|\omega_d^*|}
\]

The equation above can be simplified as

\[
I_p / I_d > \omega_p / \omega_d
\]

or

\[
V_{L1p} > V_{L1d}
\]

where \( V_{L1p} \) and \( V_{L1d} \) are the voltage drops on inductor \( L_1 \) by power carrier and data carrier respectively.

Eqn. (7) can be easily satisfied in the proposed system during data transmission since the initial voltage for communication is far less than power transfer. On the pickup side, the high frequency current of data carrier is absorbed by the parallel capacitor \( C_3 \), so it will not reach to the load and interfere with the power output.

IV. COMMUNICATION CHANNEL MODELING

In the proposed system, the bidirectional communication is achieved by the magnetic induction communication (MIC) techniques [29]. The communication antenna is the same coreless coil for power delivery. Compared with the wireless RF communication, the interaction between two sides is mainly non-radiated magnetic field couplings, and the communication channel is represented as a circuit model.

A. Forward Communication Channel

The circuit model of forward communication channel is given in Fig.7(a). Data signal is transmitted from \( V_d \) and received in \( V_r \) at the other side. In the transmitter side, the

\[
Z_{LC4}(\omega) = \frac{1}{j\omega L_{m4} + 1 / (R_m + 1 / \omega C_e + 1 / R_e)}
\]

The pickup impedance \( Z_f(\omega) \) is expressed as:

\[
Z_f(\omega) = R_e + j\omega L_m + \frac{1}{j\omega C_e + 1 / R_e} + Z_{LC4}(\omega) + R_t + j\omega L_4
\]

Fig. 7. Circuit model and bode plot of the forward channel. (a) Circuit model of the forward channel. (b) Bode plot of the forward channel (M=23mH)
For the proposed system, the value of the $Q_S$ is determined according to the requirement of data carrier amplitude by selecting proper capacitance.

The transfer gain at the data-carrier angular frequency $\omega_d$ can be simplified as follows:

$$ Z_\alpha (\omega_d) \approx j \omega_d L_2 + Z_{LC4} (\omega_d) $$

Define the signal receiver quality factor as $Q_R = \frac{Z_{LC4} (\omega_d)}{\omega_d L_m^4}$, so

$$ Z_n (\omega_d) = \frac{\omega_d^2 M^2}{Z_{\alpha} (\omega_d)} \approx - \frac{j \omega_d M^2}{L_z - j Q_{L_m} L_m^4} $$

$$ Z_p (\omega_d) \approx j \omega_d L_1 - j Q_{L_m} L_m^4 $$

Suppose $L_{d(k-4)}$ are far less than $L_{m(k-4)}$, and $G_{IC}(\omega_d)=G_{LC}(\omega_d)=1$, the gain of the forward communication channel is simplified:

$$ |G_s (\omega_d)| = \left| \frac{V_s}{V_d} \right| \approx \frac{j \omega_d M Z_{LC4} (\omega_d)}{Z_p (\omega_d) Z_{\alpha} (\omega_d)} = \frac{Q L_m L_m^4}{L_z L_2 (L_2 - j Q_{L_m} L_m^4) M} $$

From (20), two conclusions are obtained: the quality factor of the signal coupled inductor $Q_S$ is important for the gain of signal transmission; the mutual inductance of the power coupled coils has great influence for the signal transfer gain, and it can be on-line calculated according to the amplitude demodulated by the receiver circuit if all other parameters are determined.

### B. Backward Communication Channel

As depicted in Fig.8(a), the backward communication channel has similar characteristics as the forward communication channel, and the equivalent impedances are:

$$ Z_{LC3}\alpha (\omega) = \frac{1}{\frac{1}{j \omega L_{m3}} + \frac{1}{R_{m3}} + \frac{1}{j \omega C_{m3} + 1/R_m}} $$

$$ Z_{ph} (\omega) = j \omega L_4 + R_3 + j (j \omega C_3 + Z_{LC3})(\omega) + R_3 + j \omega L_{d3} $$

$$ Z_{de} (\omega) = \frac{\omega^2 M^2}{Z_{\alpha} (\omega)} $$

The transfer function of the coupled inductor $L_3$ is

$$ G_{L3\alpha} (\omega) = \frac{V_e}{V_{l3}} = \frac{1/(j \omega C_3 + 1/R_3)}{(j \omega L_{d3} + R_3 + 1/(j \omega C_3 + 1/R_3))} $$

The transfer function of the coupled inductor $L_4$ is

$$ G_{L4\alpha} (\omega) = \frac{V_e}{V_{l4}} = \frac{1/(j \omega C_4 + 1/R_4)}{(j \omega L_{d4} + R_4 + 1/(j \omega C_4 + 1/R_4))} $$

The transfer function of backward channel from the pickup side of signal transmitter coupled inductor is

$$ G_{hc} (\omega) = \frac{V_e}{V_{hc}} = \frac{1/(j \omega L_{m4} + 1/R_{m4})}{(j \omega L_{d4} + R_4 + 1/(j \omega C_4 + 1/R_4))} $$

The bode plot of the transfer function $G_{hc}(\omega)$ is shown in Fig.8(b), which shows that the system has two poles. A conventional WPT system is a narrow-band system, which usually has only one pole, the power resonant pole. For the
proposed WPT system, the transfer functions of both the forward and backward communication channels contain two poles. The one at 22.4 kHz is induced by the power resonant pole and brings about noises to communication channel, and the other one near 1.67 MHz is created for data transmission by the LC network. The available band of the proposed system is expanded by adding a high frequency pole for data transmission, which enables the system to transfer power and data via the same inductive link.

V. CROSS-TALK ANALYSIS

The cross-talk interference from the power transmission to the reliability of the bidirectional communication is analysed in this section.

As shown in Fig.9, the proposed system can be represented as a four-port network. The power is transferred from the power port 'Vp' to 'Vc', and the data is exchanged between the data ports: 'Vli' and 'Vls'. The power carrier and the data carrier, reach to each port with different transfer functions. From the analysis in Section II, the power ports are approximately short-circuited at the data-carrier frequency o_d, so the data carrier has small interference from power delivery. Nevertheless, the power carrier is a large noise for data communication, so it is important to predict the value of the cross-talk from the power transfer. 

As discussed in section III, the equivalent impedance of the communication cells can be simplified as L_s and L_d at the power-carrier frequency o_p, which means no difference between the equivalent circuit for the forward channel and backward channel.

The equivalent circuit model of the cross-talk is given in Fig.10, and the parasitic capacitance of the coils and the leakage inductance of the coupled inductors are neglected since it will not influence the following analysis.

The noise transfer function G_N3(o_p) and G_N4(o_p) are:

\[ G_{N3}(o_p) = \frac{V_{l3}(o_p)}{V_p} = \frac{j o_p L_3}{Z_p(o_p)} \] (28)

\[ G_{N4}(o_p) = \frac{V_{l4}(o_p)}{V_p} = \frac{j o_p M}{Z_p(o_p)} \] (29)

where Z_p(o_p) and Z_d(o_p) are presented in (9)-(11).

Letting L_1 + L_2 = L_1', L_2 + L_4 = L_4' and according to (2), the equations above can be calculated by:

\[ Z_p(o_p) = R_s + j o_p L_1' + \frac{1}{j o_p C_2 + 1/R_s} = R_s + \frac{j o_p L_2'}{o_p M R C_2 + 1} \] (30)

\[ Z_d(o_p) = \frac{\omega_c^2 M^2}{Z_p(o_p)} = \frac{\omega_c^2 M^2 R C_2}{L_2'} + \frac{j \omega_c^2 M^2}{L_2'} \] (31)

\[ Z_s(o_p) = R_s + \frac{\omega_c^2 M^2 R C_2}{L_2'} - \frac{j \omega_c^2 M^2}{L_2'} \] (32)

From Fig.8(a), the voltage of the primary power coil is

\[ V_{l1}(o_p) = Z_p(o_p) \frac{V_p(o_p)}{Z_p(o_p)} \] (33)

If the coupling coefficient of the power coil is small and Z_s(o_p) is ignored, from (28) and (33), it can be concluded that:

\[ \frac{V_{l1}(o_p)}{V_{l2}(o_p)} = \frac{L_2'}{L_3} \] (34)

Similarly, the voltage of the pickup side power coil is

\[ V_{l2}(o_p) = \frac{j o_p M}{Z_p(o_p)} \frac{1}{Z_s(o_p)} \frac{1}{Z_p(o_p)} = \frac{1}{Z_s(o_p)} \frac{1}{Z_p(o_p)} \] (35)

For R_s >> 1/(o_p C_2), it can be inferred

\[ \frac{V_{l4}(o_p)}{V_{l3}(o_p)} \approx \frac{L_4'}{L_3} \] (36)

Eqn. (34) and (36) can be used to estimate the cross-talk interference in a power condition, and it can be concluded that the smaller the signal coupling inductance is, the lower the crosstalk interference should be. However, for a WPT system where the inductance of the coupled coil and signal coupling inductor are predetermined, the SNR can only be increased by magnifying the output of data carrier. And yet, increasing the output of data carrier will increase the power consumed by the data communication, which will add more power losses to the system.

VI. COMMUNICATION CIRCUIT DESIGN

In the proposed scheme, half-duplex communication between the primary side and the pickup side is implemented, with the transmitter and receiver circuits are merged into the communication cells shown in Fig.11(a).

The status of the communication cells are controlled by Q_s. In receiver mode, Q_s are turned off and Q_s are turned on. In transmitter mode, Q_s are turned off, and on-off-keying (OOK) modulation is employed to transmit data. If the transmitter sends bit ‘1’, Q_s and Q_s work as complementary switch at the frequency f, for a bit-period T_b. If the transmitter sends bit ‘0’, Q_s and Q_s are turned off for a bit-period T_b. The communication rate of the system is determined by T_b, and the drive signal and output waveform of the communication cell is present in Fig11(b).
As the transmitter sends carrier signal, $Q_1$ and $Q_6$ work as complementary, and the switching duty cycle is set at 0.5 with the frequency of data carrier. The output power of the half bridge can be well-designed by selecting proper capacitance $C_s$.

When the communication cell operates in receiver mode, carrier signal from the other side is received in $V_R$ and processed by the demodulation circuits, which is illustrated in Fig.12. The data carrier is sent into a two-stage high-pass filter (HPF) at first to eliminate the power carrier, whose cut-off frequency is set at about 1MHz. The output of the HPF is processed by an envelope detector, which consists of a diode, a capacitor and a resistor, is widely used in signal demodulation for its low costs and easy implementation. The RC low-pass filter is responsible for further diminishing high frequency noise. To reach a reference voltage, the amplifier is used to amplify the data amplitude. The last part of the demodulation unit is the comparator, and the decoded data is sent to the MCU with reference voltages, which is compatible with traditional series communication interface.

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VII. EXPERIMENT VERIFICATION

A 500W prototype has been built up to verify the proposed method, with the parameters listed in Table II. The schematic circuit is the same as Fig.3, and the input voltage is 40V. The multiple-layer coils are wound on circular frames without any ferrite core. The primary side and the pickup side are controlled independently by TMS320F28035 MCUs to regulate power and data transmission.

The mutual inductance $M$ between primary and pickup sides for any position and sizes can be estimated by formula [7], but the result usually is not accurate. In this experiment, the mutual inductance of the coils is calculated according to the inductance of the coupled coils in series–aiding connection and in series–opposing connection, which is measured by LCR meter. The relationship between the coupling coefficient $k$ and the distance of the two coils is depicted in Fig.13.

The gain of the forward channel at 1.67MHz versus the air gap distance is shown in Fig.14, and the experimental results are compared with the theoretical result calculated by.
MATLAB, where the solid line is calculated from equation (15) when \( \omega = \omega_d \) and the dashed line is calculated using the simplified equation (20). Experimental results and the theoretical calculation are in good agreement, which verifies the modeling of the communication channel in section IV.

### Table III

<table>
<thead>
<tr>
<th>Frequency of ( \omega_p )</th>
<th>Frequency of ( \omega_d )</th>
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</thead>
<tbody>
<tr>
<td>( V_{L1} ) 580V</td>
<td>( 22.6V )</td>
</tr>
<tr>
<td>( V_{L2} ) 218V</td>
<td>( 1.0V )</td>
</tr>
<tr>
<td>( V_{L3} ) 14.0V</td>
<td>( 24.8V )</td>
</tr>
<tr>
<td>( V_{L4} ) 5.9V</td>
<td>( 0.95V )</td>
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The PCB board of the communication cell and the inductive coils for power and data transfer are depicted in Fig.15. The waveforms in the power coupled coils are shown in Fig.16, from which the data carrier can only be seen in the pickup side coil while backward communication, for the ratio of amplitude between data carrier and power carrier is relatively big.

Fig.17(a) shows the waveforms of forward communication at the data rate of 20kbps. The transmission distance is set 7.5cm and the coils mutual coefficient is about 0.15. \( V_{\text{dst}} \) is the bit stream sent by transmitter, and \( V_{\text{dsrc}} \) is the waveform in the signal coupling inductor at pickup side, and \( V_{\text{l1}} \) is the waveform in the signal coupling inductor at primary side, and \( V_{\text{dout}} \) is the bit stream received.

The amplitudes of frequency \( \omega_p \) and \( \omega_d \) components are listed in Table III, which is calculated by FFT according to the sampled data. It can be seen that

\[
\begin{align*}
V_{L3}(\omega_p)/V_{L3}(\omega_d) &= 0.024 \approx L_1/L_3 = 0.025 \\
V_{L4}(\omega_p)/V_{L4}(\omega_d) &= 0.027 \approx L_4/L_4 = 0.025
\end{align*}
\]

The experimental crosstalk noises are close to predicted results in (34) and (36). The data carrier transmission gain in forward channel is \( 20\log(V_{L3}(\omega_d)/V_{L3}(\omega_d)) = -28dB \), which is consistent with the analysis in communication channel modeling.

Fig.17(b) shows the waveforms of backward communication at the data rate of 20kbps, which is similar with the waveforms of forward communication.

To compare the efficiency of the proposed system with conventional WPT system, the coupled inductor in the communication board is short-circuited and the power transfer efficiency is measured. It shows that the power transfer efficiency of the proposed system is almost the same as conventional WPT system (the power of signal transfer is ignored). The reason is that the inductance of the data signal coupling inductor is small and the loss of the inductor is very low. However, the communication circuits, including modulation and demodulation circuits, need extra power source, which also bring about additional power loss. In this experiment, it achieves -16dB of SNR and consumes only 2W of additional power (0.4% of 500W power transfer), which is quite small comparing with the power transferred.

However, if applying this method to a low power system, the efficiency of power transfer would be reduced significantly. On the other side, if employing this method to WPT applications operating in several MHz range, the data carrier should operate in several 10MHz to avoid cross-talk interference, and additional circuits are needed to deal with the high frequency carrier, which increase the volume of the system. So, in low power WPT applications, this method has no advantage to conventional FSK/LSK method.
Fig. 17 Waveforms of forward and backward communication. (a) Forward communication. (b) Backward communication.

VIII. CONCLUSION

For WPT systems, communication between the primary side and the pickup side is important. This paper proposed a novel method that integrates near field communication with high power wireless power transfer. In this system, the power carrier and data carrier employ the same coil to transmit power and data by means of frequency division duplexing. The performance of the power and data transfer, as well as the cross-effect between power transfer and data communication, are analysed in detail. It has been shown that the power and data can share a pair of common coupled coils and be controlled independently. The results obtained from a 500W experimental platform are in line with the theoretical analysis, which verify the effectiveness of the proposed method.

The communication channel between two sides, which has acquired 20kbps data rate in this paper, can be used for close-loop control. In pickup side, the output voltage and current are sampled and send back to primary side, and then the controller in primary side changes its frequency to regulate the output voltage or current in pickup side. For WPT system with about 20kHz power carrier, the 20kbps data rate is fast enough for the control loop, and it can be promoted by increasing the carrier frequency and improving the modulation/demodulation method. Another potential application of this method is that the bit stream of communication can be employed as a synchronous clock for bidirectional WPT. On the other side, the mutual inductance of the coils can be calculated by measuring the amplitude of the received data carrier, which can be utilized to improve power control strategy.

The proposed method aims for the applications of high power WPT with low frequency. However, due to the power losses in communication resonant tank, the total efficiency of the WPT system decreases slightly, so that this method is not suitable for the communication in low power WPT system with high frequency carrier, which is dominated by FSK/LSK method.

REFERENCES

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